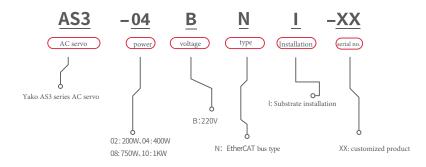
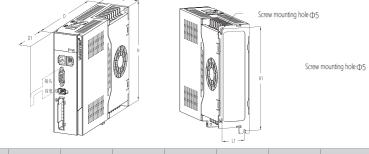
Servo Drive Naming Rules



Drive Specs and Dimensions



Model	L(mm)) H(mm) D(mm		L1(mm)	H1(mm)	D1(mm)	screw hole	
AS3 Frame B	40	170	163	28	161	75	2-M4	
AS3 Frame C	50	170	173	37	161	75	2-M4	

Structure Size		SIZE B	SIZE C					
Drive Model	AS3-02BNI	AS3-04BNI	AS3-08BNI	AS3-10BNI 6.0 17				
Output Current Arms	1.6	2.8	5.0					
Maximum Output Current Arms	5.8	10	13.5					
Main Circuit Power Supply	Single-phase AC200V-240V							
Regenerative Loop Function	External brake resistor							
Control Circuit Power Supply	single-phase AC200V-240V,+10%~-10%,50/60Hz							

Servo Drive Basic Specifications

$ \begin{array}{ c c c c } \medskip \meds$	 Basic Specific 	ations						
Working Environment Image: Storage: -20° C-70°C Humidity $O \sim 90\%$ RH/L/T Working Allitude <1000 mabove sea level		Temperature	2	Operating: 0°C~+50°C (if it's in 45°C~55°C, the average load rate should <80%				
Working Environment Working Allitude Working Allitude <1000m above sea level				Storage: -20°C~70°C				
Environment Vibration/Shock vibration : < 4.9m/s ² impact: < 19.6m/s ³ IP Rating/Pollution degree IP20/Pollution degree 2 IGBT PWM space vector control Encoder IGST PWM space vector control Input Input and output port IOsignal Input 5 (General) Output 3 (General) Output 3 (General) Communication Function RS232 (USS) Connect with PC for debugging servo drive ED display Regenerative Loop Function Regrementive Loop Function Over current, overload, over voltage, low voltage, over speed, over temperat encoder abnormality, communication abnormality, eccessive position devia Control mode Smoothing Filter Contour Position Mode (PP) ; Contour Speed Mode (PV) ; Contour Torque Mode (PT) ; Position Command Format EtherCAT bas digital smoothing filter Vibration Suppression Filter Ina discharg upges actual guati interfere and span mosance fragment, to enser state operation of the discharg upges actual span format and span mosance fragment, to enser state operation of the discharg upges actual span format and span mosance fragment, to enser state operation of the discharg upges actual span format and span mosance fragment, to enser state operation of the discharg upges actual span format and span format actual span format and span forma task of the disginal Speed		Humidity		0~90% RH以下				
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	Environment	Vibration/Shock		vibration: $< 4.9 \text{m/s}^2$ impact: $< 19.6 \text{m/s}^2$				
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Input and output port	Con	Ū.	intuon degree	IGBT PWM space vector control				
$ \begin{array}{ c c c c } \medskip \meds$	En	coder		17-bit incremental / 23-bit absolute				
Communication Function RS232 (USB) Connect with PC for debugging serve drive Panel Operator LED display Regenerative Loop Function Built-in braking resistor for >1000W Protect Function Over current, overload, over voltage, low voltage, over speed, over temperat encoder abnormality, communication abnormality, excessive position devia Control mode Contour Position Mode (PP) ; Contour Speed Mode (PV) ; Contour Torque Mode (PT) ; Position Command Format EtherCAT bas digital Position Control Mode Smoothing Filter Smoothing Filter Smoothing Filter Notifications Smoothing Filter Vibration Suppression Filter Rate Notification Voltage Rate Command Form EtherCATbus digital Voltage Voltage Rate Oltage Speed Control Mode Command Form EtherCATbus digital Voltage Interpretation Command Form EtherCATbus digital Temperature Speed Control Mode Command Form EtherCATbus digital Temperature Internet to zero mode Command Form EtherCAT bus digital Zero return method setting <tr< td=""><td></td><td></td><td>Input</td><td>5 (General)</td></tr<>			Input	5 (General)				
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Speed Control Mode Voltage Fluctuation Rated voltage±10%: 0.5% (Rated speed) Speed Change Rate Load Fluctuation 0-100% load: $\leq 0.5\%$ (Rated speed) Temperature 25±25°C: $\leq 0.5\%$ (Rated speed) Acceleration Deceleration Setting Range 0-10S Torque Control Mode Command Form EtherCAT bus digital Return to zero mode Command Form EtherCAT bus digital Zero return method setting Through the EtherCAT bus configuration, Self-tuning Function support a variety of zero return mode Inertia Encoder Feedback Electronic Gear identification, rigidity tuning Abnormal Information Record Setting freely								
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Common Abnormal Information Record Setting freely		~						
8 groups of historical information records	Common	Abnormal Infor	mation Record					
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		dyna	umic braking	e group of motorical mornadon records				

Servo Drive Connection to Peripheral Devices



Servo Drive Terminal Definition

Function

Home switch

Probe 2

Probe 1

Forward drive forbidden

Backward drive forbidden

Internal 24V power supply, voltage range

No definition; For the motor with

brake, the function code P02.23

should set as 11 for the brake output

internal 24V ground; open collector pulse input ground

Power input, 12~24V

Servo ready

Position reached

+20~28V, Maximum output current 200mA

CN1 Control Terminal - General Input and Output Signal

Definition PIN

10

9

8

7

11

15

14

13

1 S-RDY+

6 S-RDY-

3

2

5

4

P-OT

N-OT

Home

Switch

Touch

Probe2

Touch

Probe1

COIN+

COIN-

DI1

DI2

DI3

DI4

DI5

+24

COM_24

IN_COM

DO1+

D01-

DO2+

D02-

DO3+

DO3-

CN2 Encoder Cable Servo Driver Side Terminal Pin Distribution

PIN	Encoder Signal	Function
1	+5V	+5V Power Output
2	GND	power GND output
5	SD+	
6	SD-	Encoder Signal
Shell	PE	

CN3 and CN4 - Industrial Bus Communication Port Uses

PIN	Color Signal	Name	Direction
1	white/orange	TxData+	Output
2	orange	TxData-	Output
3	white/green	RecvData+	Input
4	blue	Unused	Unused
5	white/blue	Unused	Unused
6	green	RecvData-	Input
7	white/brown	Unused	Unused
8	brown	Unused	Unused

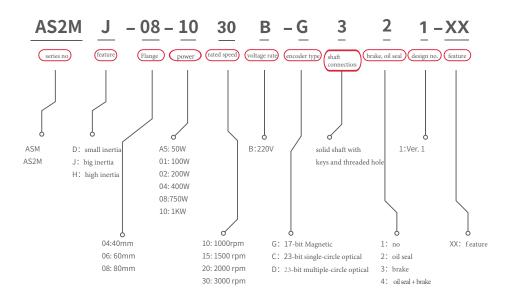
Main Circuit Terminal Definition

Name	Terminal Mark	Function Specification						
Control Power Input Terminal	L1,L2	Control circuit power input terminal						
External Regenerative Resistor Connection Terminal	P.D.C	For the IKw molds, P and D are short commeted by default, and the buffs in resistor has been connected. When the braking capacity is issufficient, please context the external brake resistance between P and C (to use the external resistance, remove the short wiring and keep P and D open). For 400W models, P and C are equipped with external brake resistance, so D terminal is unavailable.						
Common DC Bus Terminal	P、N	Common bus connection when multiple units are connected in parallel						
Servo Motor Connection Terminal	U,V,W	Servo motor connection terminal, connected to U, V, W.						
Ground Terminal	PE	Two grounding terminals are connected to the power grounding terminal and the motor grounding terminal. Be sure to ground the entire system.						

Servo System Configuration Table

	Single	220V	
	F		
	Size B		Size C
AS3-02BNI	AS3-04BNI	AS3-08BNI	AS3-10BNI
ASMD-04-A530B AS2MD-04-0130B AS2MJ-06-0230B	AS2MJ-06-0430B	AS2MJ-08-0830B	AS2MJ-08-0830B AS2MJ-08-1030B

Motor Naming Rules



Motor Parameters

	1				1 1					
Parameters	Rated Output	Rated Torque	Maximum Torque	Rated Current	Maximum Current	Rated Speed	Maximum Speed	Rotor Inertia	Voltage	Matched Drive Mod
model	(KW)	(Nm)	(Nm)	(Arms)	(Arms)	(rpm)	(rpm)	(10 ⁻⁴ Kgm ²)	(Kg)	
			17-bit B	Encoder M	otor Parame	ters				
				40 Fla	ange					
ASMD-04-A530B-G311	0.05	0.159	0.477	0.67	2.01	3000	5000	0.025	0.4	AS3-02BNI
AS2MD-04-0130B-G321	0.1	0.318	0.954	1.26	3.78	3000	5000	0.043	0.45	AS3-02BNI
				60 Fla	ange					
AS2MJ-06-0230B-G321	0.2	0.64	1.92	1.67	5.1	3000	5000	0.32	0.93	AS3-02BN
AS2MJ-06-0430B-G321	0.4	1.27	3.81	2.5	7.5	3000	5000	0.57	1.26	AS3-04BNI
				80 Fla	ange					
AS2MJ-08-0830B-G321	0.75	2.39	7.17	4.8	14.4	3000	5000	1.69	2.8	AS3-08BN AS3-10BN
AS2MJ-08-1030B-G321	1.0	3.18	9.52	6.3	18.9	3000	5000	2.1	2.9	AS3-10BN
			23-bit	Encoder M	otor Parame	eters				
				40 Fla	ange					
AS2MD-04-0130B-D321	0.1	0.318	0.954	1.26	3.78	3000	7000	0.043	0.45	AS3-02BNI
				60 Fla	inge					
AS2MJ-06-0230B-D321	0.2	0.64	1.92	1.67	5.1	3000	7000	0.32	0.93	AS3-02BNI
AS2MJ-06-0430B-C321	0.4	1.27	3.81	2.5	7.5	3000	7000	0.57	1.26	AS3-04BNI
AS2MJ-06-0430B-D321	0.4	1.27	3.81	2.5	7.5	3000	7000	0.57	1.26	AS3-04BNI
				80 Fla	ange					
AS2MJ-08-0830B-C321	0.75	2.39	7.17	4.8	14.4	3000	6500	1.69	2.8	AS3-08BNI AS3-10BNI
AS2MJ-08-0830B-D321	0.75	2.39	7.17	4.8	14.4	3000	6500	1.69	2.8	AS3-08BNI AS3-10BNI
AS2MJ-08-1030B-D321	1.0	3.18	9.52	6.3	18.9	3000	6500	2.1	2.9	AS3-10BNI